

Capacity Bounds for the Hard-Triangle Model

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I. INTRODUCTION

Two-dimensional constraints play a role in optical storage devices. In particular, run length constraints in one and higher dimensions have been a subject of intense research. In two dimensions, such constraints have primarily been studied for rectangular and hexagonal lattices. We examine such constraints for an equilateral triangular non-lattice tiling of the two-dimensional plane.

A binary sequence satisfies a *one-dimensional* (d, k) *run length constraint* if there are at most k zeros in a row, and between every two consecutive ones there are at least d zeros. A two-dimensional binary rectangular array is said to satisfy a *two-dimensional* (d, k) *run length constraint*, if it satisfies the one-dimensional (d, k) run length constraint along the directions parallel to the coordinate axes. Such an array is called (d, k) -*valid*. The number of (d, k) -valid two-dimensional arrays of size $m \times n$ is denoted by $\nu_{d,k}(m, n)$ and the corresponding *capacity* is defined as $C_{d,k}^{(2)} = \lim_{m,n \rightarrow \infty} \frac{\log_2 \nu_{d,k}(m, n)}{mn}$.

Here, we consider a non-lattice tiling of the two-dimensional plane by equilateral triangles and use the center of each triangle to store a bit. Analogous to the square and hexagonal cases, we study a “hard triangle” constraint on the triangular tiling. Every triangle with a 1 in it must have all three of its neighboring triangles have 0s in them. We analyze the capacity by deriving an upper bound analytically and obtain a lower bound by exhibiting a bit stuffing algorithm for encoding arbitrary input binary sequences into the triangular tiling without violating the constraint.

II. DEFINITIONS

For any $i, j \in \mathbf{Z}$, let $[i, j] = i(\frac{\sqrt{3}}{2}, 0) + j(\frac{\sqrt{3}}{2}, \frac{3}{2})$, $[i, j]' = [i, j] + (0, 1)$, $T_1 = \{[i, j] : i, j \in \mathbf{Z}\}$, $T_2 = T_1 + (0, 1)$, $T = T_1 \cup T_2$. The notation $[i, j]$ represents a point in T_1 with respect to the basis $\{(\frac{\sqrt{3}}{2}, 0), (\frac{\sqrt{3}}{2}, \frac{3}{2})\}$. We say that two points (or their corresponding triangles) in T are *neighbors* if the distance between them is 1.

For any $S \subset T$, a function $f : S \rightarrow \{0, 1\}$ is called a *labeling* of S . A labeling f of S satisfies the *hard-triangle constraint* if for every $t \in S$, the three nearest neighbors of t are labeled with 0s whenever $f(t) = 1$. In what follows, we will call a labeling of S *valid* if it satisfies the hard-triangle constraint, and will denote the set of valid labelings by $L(S)$. The capacity of the hard-triangle constraint will be defined analogously to the hard-square constrained capacity.

For $X, Y \in \mathbf{Z}^+$, define the array $A_{X,Y} \subset T$ as

$$A_{X,Y} = \{[i, j] : 0 \leq i \leq X, 0 \leq j \leq Y\} \\ \cup \{[i, j]' : 0 \leq i \leq X, -1 \leq j \leq Y - 1\}$$

and let $\nu(X, Y)$ denote the number of valid labelings of $A_{X,Y}$. The capacity C_T corresponding to the hard-triangle constraint is defined as

$$C_T = \lim_{X,Y \rightarrow \infty} \frac{\log_2 \nu(X, Y)}{|A_{X,Y}|} = \lim_{X,Y \rightarrow \infty} \frac{\log_2 \nu(X, Y)}{2(X+1)(Y+1)}$$

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where the right hand side follows since the size of $A_{X,Y}$ is $2(X+1)(Y+1)$.

III. HARD-TRIANGLE CAPACITY UPPER BOUND

Let $f_1, f_2, \dots, f_{\nu(0,Y)}$ denote the valid labelings of $A_{0,Y}$. Define the *transfer matrix* M_Y to be a $\nu(0, Y) \times \nu(0, Y)$ binary matrix, such that the rows and columns of M_Y are indexed by the valid labelings of $A_{0,Y}$, and the $(i, j)^{th}$ entry of M_Y is 1 if and only if the labeling of $A_{0,Y}$ and $A_{0,Y} + [1, 0]$ defined by $f_i(u)$ and $f_j(u - [1, 0])$, respectively, is valid on $A_{0,Y} \cup (A_{0,Y} + [1, 0])$. Then, $\nu(X, Y) = \mathbf{1}' \cdot M_Y^{X-1} \cdot \mathbf{1} = \mathbf{1}' \cdot M_X^{Y-1} \cdot \mathbf{1}$ where $\mathbf{1}$ is the all-ones column vector of the appropriate dimension and prime denotes transpose. The matrix M_Y meets the conditions of the Perron-Frobenius theorem [1, p. 17], since it has nonnegative elements and is irreducible. The largest magnitude eigenvalue Λ_Y of M_Y is positive, real, and has multiplicity one, and $\lim_{X \rightarrow \infty} (\nu(X, Y))^{1/X} = \Lambda_Y$. Furthermore, any valid labeling of $A_{X, k(Y+1)-1}$ defines a valid labeling of $A_{X, Y} + i(Y+1)[0, 1]$ whenever $0 \leq i < k$, and therefore $\nu(X, kY) \leq (\nu(X, Y))^k$. Hence, for any $Y \geq 0$,

$$C_T = \lim_{X,k \rightarrow \infty} \frac{\log_2 \nu(X, kY)}{2k(X+1)(Y+1)} \\ \leq \frac{1}{2(Y+1)} \lim_{X \rightarrow \infty} \log_2 (\nu(X, Y))^{1/(X+1)} = \frac{\log_2 \Lambda_Y}{2(Y+1)}.$$

Thus the sequence $\{\log_2 \Lambda_i / (2(i+1))\}$ converges to C_T from above. Using Λ_{13} above gives $C_T \leq 0.634775895$.

IV. HARD-TRIANGLE CONSTRAINED ENCODING

To obtain a lower bound on the capacity C_T , we introduce the notion of a hard-triangle constrained encoder. The encoder maps a random sequence \hat{w} of independent bits with the probability of a 0 equal 1/2 into a hard-triangle constrained labeling of T . Then we calculate the coding rate of the encoder. The coding rate is a quantity that measures the efficiency of the encoder, and is known [2, p. 27] to be upper-bounded by the capacity C_T .

A hard-triangle constrained *encoder* is an injection $\mathcal{E} : \{0, 1\}^\infty \rightarrow \bigcup_{S \subset T} L(S)$ and its inverse is called a *decoder*. The encoder \mathcal{E} maps an infinite binary input sequence into a labeling of a subset of T . An encoder and decoder are together called a *coding algorithm*.

Theorem 1 *The hard-triangle constrained encoder \mathcal{E} achieves a coding rate of $r = 0.628831217$, which is within 1% of the capacity.*

Corollary 2 *The capacity C_T of the hard-triangle constraint is bounded as $0.628831217 \leq C_T \leq 0.634775895$.*

REFERENCES

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